

Course Code	TKEE163125													
Course Name	Advanced Control Systems													
Course Instructors	Adha Imam Cahyadi													
Course Type	Selected Elective													
Course Classification	Engineering Topics													
Credit / Contact Hour per Week	2 / 100 minutes per Week													
Course Description	<i>Understand about the concepts of controlling especially in frequency approach, also with its analyses and syntheses.</i>													
Prerequisites Courses	<i>Linear Algebra, Engineering Mathematics, Mathematics for Electrical Engineer, Engineering Physics, Physics for Electrical Engineer, Control Systems</i>													
<b>Covered Student Outcome</b>	<b>Development of Engineering Solution (b) Engineering Design (c)</b>													
Learning Outcome	<ol style="list-style-type: none"> <li>1. Students are able to model the real system in a nonlinear differential equations lumped parameter, able to linearize and change to linear state space model, transfer function and vice versa.</li> <li>2. Students are able to use mathematics and linear algebra to analyze linear state space equation.</li> <li>3. Students are able to calculate state transition matrix and understand the realization.</li> <li>4. Students are able to understand concepts of LTI systems stability.</li> <li>5. Students are able to apply the concepts of Controllability and Observability and its dual condition.</li> <li>6. Students are able to design state feedback compensator and state estimator</li> </ol>													
Topic	<p>Analysis of Control Systems in State Space</p> <ul style="list-style-type: none"> <li>• Introduction</li> <li>• State-Space Representations of Transfer-Function Systems</li> <li>• Solving the Time-Invariant State Equations</li> <li>• Some Useful Results in Vector-Matrix Analysis</li> <li>• Controllability</li> <li>• Observability</li> </ul> <p>Norm of signal  basic concept: stability, internal stability, asymptotic tracking  uncertainty and robustness  stabilization  design concept under model uncertainty</p>													
Direct Assessment	<table border="1"> <thead> <tr> <th>Direct Assessment Plan</th> <th>Measured Learning Outcome</th> </tr> </thead> <tbody> <tr> <td>Engineering Design Assignment – Creating Proof of Concept</td> <td>LO2, LO4</td> </tr> <tr> <td>Engineering Design Assignment – Presenting the solution</td> <td>LO3</td> </tr> <tr> <td>Mid Exam</td> <td>LO1, LO2, LO3</td> </tr> <tr> <td>Final Exam</td> <td>LO4, LO5, LO6</td> </tr> <tr> <td></td> <td></td> </tr> </tbody> </table>		Direct Assessment Plan	Measured Learning Outcome	Engineering Design Assignment – Creating Proof of Concept	LO2, LO4	Engineering Design Assignment – Presenting the solution	LO3	Mid Exam	LO1, LO2, LO3	Final Exam	LO4, LO5, LO6		
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Indirect Assessment	Questionnaire (EDOM)													
References	<p>[1] Chen, Chi-Tsong. <i>Linear system theory and design</i>. Oxford University Press, Inc., 1995.</p> <p>[2] Nise, Norman S. <i>CONTROL SYSTEMS ENGINEERING</i>, John Wiley &amp; Sons, 2007.</p> <p>[3] Ogata, Katsuhiko. <i>Modern control engineering</i>. Prentice Hall PTR, 2001.</p> <p>[4] Dorf, Richard C., and Robert H. Bishop. <i>Modern control systems</i>. Prentice</p>													

	Hall, 2011.
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